Plotting Realistic Instantaneous Field of View Ellipsoids on an Arbitrary Earth Projection

Thomas J. Kleespies
NOAA/NESDIS
Camp Springs, Maryland USA

Introduction

The ability to draw realistic fields of view (fov) in an arbitrary earth projection has a number of uses. It can be used with coastlines to assess the geolocation and pointing accuracy of an instrument. In conjunction with surface type atlases, it can help in estimating surface emissivity and land fraction. It can also be used to easily co-locate disparate instruments from different platforms. This paper outlines a method for performing this function. The mathematical derivation is not given here, but will be published in the open literature.

Description of the technique

The fov of most nadir scanning satellite instrument normally is circular at nadir and increases in size both along and cross track as the scan angle increases. The cross track distortion is due to the fact that the fov edge closer to nadir is also farther away from the horizon, which causes a stretching of the fov. In fact the distance from the fov center to the edge farthest from nadir is larger than the distance from the fov center to the edge closest to nadir. The along track distortion is simply due to the fact that fov angle is fixed, but the distance from the satellite to the viewing location on the earth increases as the scan moves away from nadir. The technique used to produce the figures shown here assumes a spherical earth, that topography can be neglected, that the field of view can be represented by an ellipse, that the satellite attitude is nominal, that the satellite height and sub point are known, and that the location of the centers of the individual fields of view are known. The ellipse semi-major and semi-minor axes are computed from known satellite height and scan angles via plane trigonometry. The rotation of the ellipse with respect to latitude parallels is computed from the sub-satellite point and the fov location via spherical trigonometry. Finally, the ellipsoid is approximated by a polygon of an arbitrary number of sides using the equation of an ellipse in polar coordinates. Examples of these plots are given in the figures below.

Acknowledgments

The views expressed in this publication are those of the author and do not necessarily represent those of NOAA.
Figure 1: NOAA-17 AMSU-A and AMSU-B scan pattern in cylindrical coordinates. Coastline is North New Guinea.

Figure 2: NOAA-17 AMSU-A and AMSU-B scan patterns near the north pole in polar stereographic coordinate.
Figure 3. Hypothetical 40 km nadir resolution geosynchronous sounder scan pattern in a satellite coordinate system.

Figure 4. Hypothetical 40 km nadir resolution geosynchronous sounder scan pattern in a cylindrical coordinate system.
Proceedings of the Fourteenth International TOVS Study Conference

Beijing, China
25-31 May 2005